

# Switch Fabrics

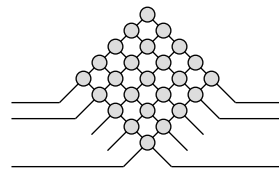
Switching Technology S38.165  
<http://www.netlab.hut.fi/opetus/s38165>

## Switch fabrics

- Basic concepts
- Time and space switching
- Two stage switches
- Three stage switches
- **Cost criteria**
- Multi-stage switches and path search

## Cost criteria for switch fabrics

- Number of cross-points
- Fan-out
- Logical depth
- Blocking probability
- Complexity of switch control
- Total number of connection states
- Path search



## Cross-points

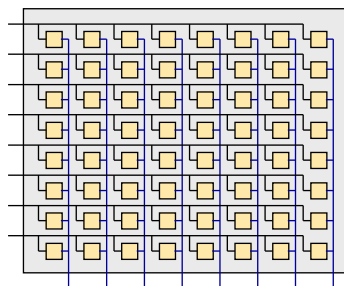
- **Number of cross-points gives the number of on-off gates (usually “and-gates”) in space switching equivalent of a fabric**
  - minimization of cross-point count is essential when cross-point technology is expensive (e.g. electro-mechanical and optical cross-points)
  - Very Large Scale Integration (VLSI) technology implements cross-point complexity in Integrated Circuits (ICs)  
=> more relevant to minimize number of ICs than number of cross-points
  - Due to increasing switching speeds, large fabric constructions and increased integration density of ICs, power consumption has become a crucial design criteria
    - higher speed => more power
    - large fabrics => long buses, fan-out problem and more driving power
    - increased integration degree of ICs => heating problem

## Fan-out and logical depth

- VLSI chips can hide cross-point complexity, but introduce pin count and fan-out problem
  - length of interconnections between ICs can be long lowering switching speed and increasing power consumption
  - parallel processing of switched signals may be limited by the **number** of available **pins** of ICs
  - **fan-out** gives the driving capacity of a switching gate, i.e. number of inputs (gates/cross-points) that can be connected to an output
  - long buses connecting cross-points may lower the number of gates that can be connected to a bus
- Logical depth gives the number of cross-points a signal traverses on its way through a switch
  - large logical depth causes excessive delay and signal deterioration

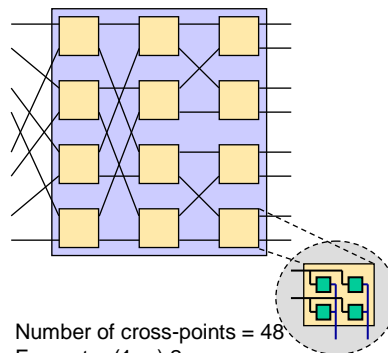
## Illustration of cross-points, fan-out and logical depth

An 8x8 crossbar



Number of cross-points = 64  
Fan-out = 8  
Logical depth = 1

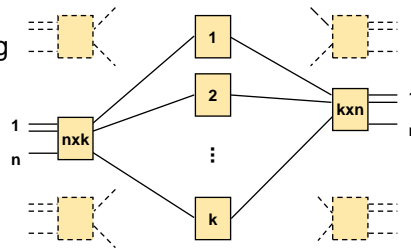
An 8x8 banyan



Number of cross-points = 48  
Fan-out = (1 or) 2  
Logical depth = 3

## Blocking probability

- Blocking probability of a multi-stage switching network difficult to determine
- Lee's approximation gives a coarse measure of blocking
- Assume uniformly distributed load
  - equal load in each input
  - load distributed uniformly among intermediate stages (and their outputs) and among outputs of the switch
- Probability that an input is engaged is  $a = \lambda S$  where
  - $\lambda$  = input rate on an input link
  - $S$  = average holding time of a link



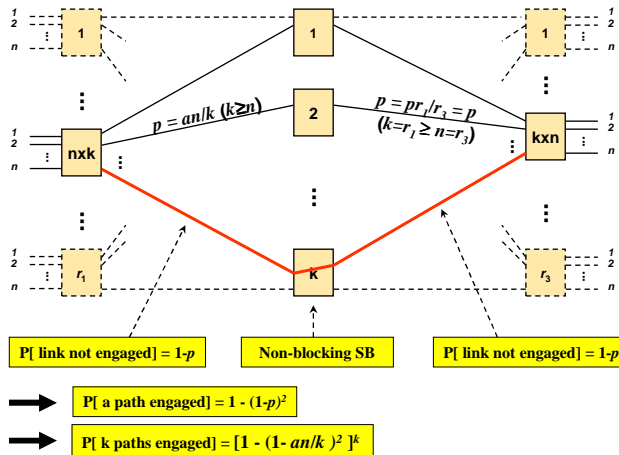
## Blocking probability (cont.)

- Under the assumption of uniformly distributed load, probability that a path between any two switching blocks is engaged is  $p = an/k$  ( $k \geq n$ )
- Probability that a certain path from an input block to an output block is engaged is  $1 - (1-p)^2$  where the last term is the probability that both (input and output) links are disengaged
- Probability that all  $k$  paths between an input switching block and an output switching block are engaged is

$$B = [1 - (1 - an/k)^2]^k$$

which is known as Lee's approximation

## Blocking probability (cont.)



## Control complexity

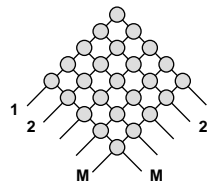
- Given a graph  $G$ , a control algorithm is needed to find and set up paths in  $G$  to fulfill connection requirements
- Control complexity is defined by the hardware (computation and memory) requirements and the run time of the algorithm
- Amount of computation depends on blocking category and degree of blocking tolerated
- In general, computation complexity grows exponentially as a function of the number of terminals
- There are interconnection networks that have a regular structure for which control complexity is substantially reduced
- There are also structures that can be distributed over a large number of control units

## Management complexity

- **Network management** involves adaptation and maintenance of a switching network after the switching system has been put in place
- Network management deals with
  - failure events and growth in connectivity demand
  - changes of traffic patterns from day to day
  - overload situations
  - diagnosis of hardware failures in switching system, control system as well as in access and trunk network
    - in case of failure, traffic is rerouted through redundant built-in hardware or via other switching facilities
    - diagnosis and failure maintenance constitute a significant part of software of a switching system
  - In order for switching cost to grow linearly in respect to total traffic, switching functions (such as control, maintenance, call processing and interconnection network) should be as modular as possible

## Example 1

- A switch with
  - a capacity of  $N$  simultaneous calls
  - average occupancy of lines during a busy hour is  $X$  Erlangs
  - $Y\%$  requirement for internal use
  - notice that two (one-way) connections are needed for a call
 requires a switch fabric with  $M = 2 \times [(100+Y)/100] \times (N/X)$  inputs and outputs.
- If  $N = 20\,000$ ,  $X = 0.72$  Erl. and  $Y = 10\%$ 
  - $\Rightarrow M = 2 \times 1.1 \times 20\,000/0.72 = 61\,112$
  - $\Rightarrow$  corresponds to 2038 E1 links



## Amount of traffic in Erlangs

- Erlang defines the amount of traffic flowing through a communication system - it is given as the aggregate holding time of all channels of a system divided by the observation time period
- Example 1:  
During an hour period three calls are made (5 min, 15 min and 10 min) using a single telephone channel => the amount of traffic carried by this channel is (30 min/60 min) = 0.5 Erlang
- Example 2:  
A telephone exchange supports 1000 channels and during a busy hour (10.00 - 11.00) each channel is occupied 45 minutes on the average => the amount of traffic carried through the switch during the busy hour is (1000x45 min / 60 min) = 750 Erlangs

## Erlang's first formula

### Erlang 1st formula

$$E_1(n, A) = \frac{\frac{A^n}{n!}}{1 + A + \frac{A^2}{2!} + \dots + \frac{A^n}{n!}}$$

- Erlang 1st formula applies to systems fulfilling conditions
  - a failed call is disconnected (loss system)
  - full accessibility
  - time between subsequent calls vary randomly
  - large number of sources
- $E_1(5, 2.7)$  implies that we have a system of 5 inlets and offered load is 2.7 Erlangs - blocking calculated using the formula is 8.5 %
- Tables and diagrams (based on Erlang's formula) have been produced to simplify blocking calculations

## Example 2

- An exchange for 2000 subscribers is to be installed and it is required that the blocking probability should be below 10 %. If E1 links are used to carry the subscriber traffic to telephone network, how many E1 links are needed ?
  - average call lasts 6 min
  - a subscriber places one call during a 2-hour busy period (on the average)
- Amount of offered traffic is  $(2000 \times 6 \text{ min} / 2 \times 60 \text{ min}) = 100 \text{ Erl.}$
- Erlang 1st formula gives for 10 % blocking and load of 100 Erl. that  $n = 97$   
 $\Rightarrow$  required number of E1 links is  $\text{ceil}(97/30) = 4$

## Example 3

- Suppose that driving current of a switching gate (cross-point) is 100 mA and its maximum input current is 8 mA
  - How many output gates can be connected to a bus, driven by one input gate, if the capacitive load of the bus is negligibly small ?
  - Fan-out =  $\text{floor}[100/8] = 12$
- 
- How many output gates can be connected to a bus driven by one input gate if load of the bus corresponds to 15 % of the load of a gate input) ?
  - Fan-out =  $\text{floor}[100/(1.15 \times 8)] = 10$



## Switch fabrics

- Basic concepts
- Time and space switching
- Two stage switches
- Three stage switches
- Cost criteria
- **Multi-stage switches and path search**

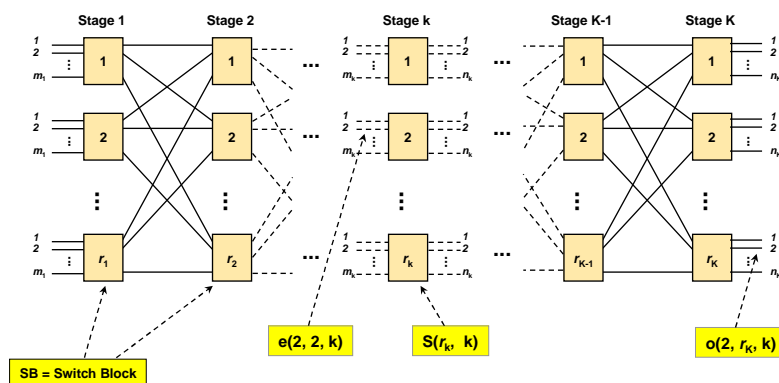
## Multi-stage switching

- Large switch fabrics could be constructed by using a single  $N \times N$  crossbar, interconnecting  $N$  inputs to  $N$  outputs
  - such an array would require  $N^2$  cross-points
  - logical depth = 1
  - considering the limited driving power of electronic or optical switching gates, large  $N$  means problems with signal quality (e.g. delay, deterioration)
- Multi-stage structures can be used to avoid the problems
- Major design problems with multi-stages
  - find a non-blocking structure
  - find non-conflicting paths through the switching network

## Multi-stage switching (cont.)

- Let's take a network of  $K$  stages
- Stage  $k$  ( $1 \leq k \leq K$ ) has  $r_k$  **switch blocks (SB)**
- Switch block  $j$  ( $1 \leq j \leq r_k$ ) in stage  $k$  is denoted by  $S(j, k)$
- Switch  $j$  has  $m_k$  inputs and  $n_k$  outputs
- Input  $i$  of  $S(j, k)$  is represented by  $e(i, j, k)$
- Output  $i$  of  $S(j, k)$  is represented by  $o(i, j, k)$
- Relation  $o(i, j, k) = e(i', j', k+1)$  gives interconnection between output  $i$  and input  $i'$  of switch blocks  $j$  and  $j'$  in consecutive stages  $k$  and  $k+1$
- Special class of switches:
  - $n_k = r_{k+1}$  and  $m_k = r_{k-1}$
  - each SB in each stage connected to each SB in the next stage

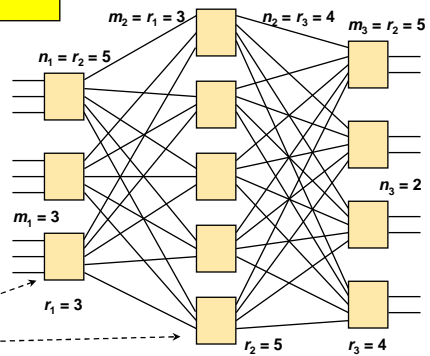
## Multi-stage switching (cont.)



## Clos network

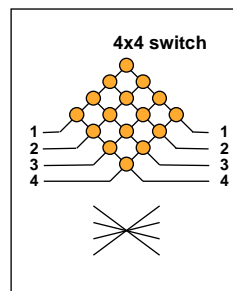
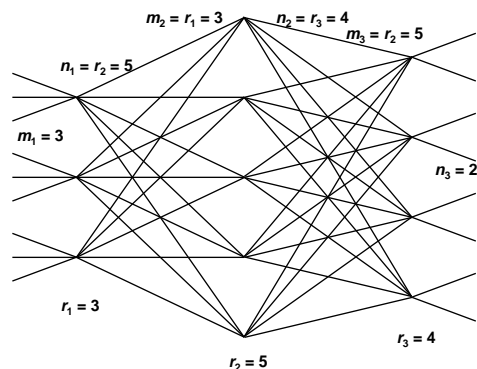
$m_k$  = number of inputs in a SB at stage  $k$   
 $n_k$  = number of outputs in a SB at stage  $k$   
 $r_k$  = number of SBs at stage  $k$

- parameters  $m_1, n_3, r_1, r_2, r_3$  chosen freely
- other parameters determined uniquely by  $n_1 = r_2, m_2 = r_1, n_2 = r_3, m_3 = r_2$



SB = Switch Block

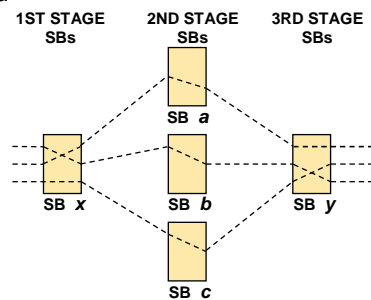
## Graph presentation of a Clos network



Every SB in stage  $k$  is connected to all  $r_{k+1}$  SBs in the following stage  $k+1$  with a single link.

## Path connections in a 3-stage network

- An input of SB  $x$  may be connected to an output of SB  $y$  via a middle stage SB  $a$
- Other inputs of SB  $x$  may be connected to other outputs of SB  $y$  via other middle stage SBs ( $b, c, \dots$ )
- Paull's connection matrix is used to represent paths in three stage switches



## Paull's matrix

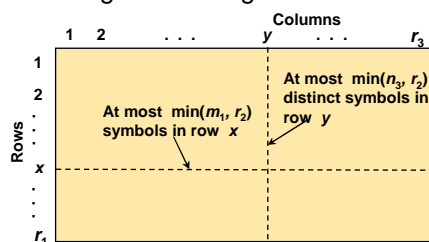
- Middle stage switch blocks ( $a, b, c$ ) connecting 1st stage SB  $x$  to 3rd stage SB  $y$  are entered into entry  $(x,y)$  in  $r_1 \times r_3$  matrix
- Each entry of the matrix may have 0, 1 or several middle stage SBs
- A symbol ( $a,b,\dots$ ) appears as many times in the matrix as there are connections through it

|                       |       | Stage 3 switch blocks |   |     |           |     |       |
|-----------------------|-------|-----------------------|---|-----|-----------|-----|-------|
|                       |       | 1                     | 2 | ... | $y$       | ... | $r_3$ |
| Stage 1 switch blocks | 1     |                       |   |     |           |     |       |
|                       | 2     |                       |   |     |           |     |       |
|                       | ...   |                       |   |     |           |     |       |
|                       | $x$   |                       |   |     | $a, b, c$ |     |       |
|                       | ...   |                       |   |     |           |     |       |
|                       | ...   |                       |   |     |           |     |       |
|                       | $r_1$ |                       |   |     |           |     |       |

## Paull's matrix (cont.)

### Conditions for a legitimate point-to-point connection matrix:

- 1 Each row has at most  $m_1$  symbols, since there can be as many paths through a 1st stage SB as there are inputs to it
- 2 Each column has at most  $n_3$  symbols, since there can be as many paths through a 3rd stage SB as there are outputs from it



## Paull's matrix (cont.)

### Conditions of a legitimate point-to-point connection matrix (cont.):

- 3 Symbols in each row must be distinct, since only one edge connects a 1st stage SB to a 2nd stage SB  
=> there can be at most  $r_2$  different symbols in each row
- 4 Symbols in each column must be distinct, since only one edge connects a 2nd stage SB to a 3rd stage SB and an edge does not carry signals from several inputs  
=> there can be at most  $r_2$  different symbols in each column

**In case of multi-casting, conditions 1 and 3 may not be valid, because a path from the 1st stage may be directed via several 2nd stage switch blocks. Conditions 2 and 4 remain valid.**

## Strict-sense non-blocking Clos

### Definitions:

- $T'$  is a subset of set  $T$  of transmitting terminals
- $R'$  is a subset of set  $R$  of receiving terminals
- Each element of  $T'$  is connected by a legitimate multi-cast tree to a non-empty and disjoint subset  $R'$
- Each element of  $R'$  is connected to one element of  $T'$

A network is **strict sense non-blocking** if any  $t \in T - T'$  can establish a legitimate multi-cast tree to any subset  $R - R'$  without changes to the previously established paths.

A **rearrangeable** network satisfies the same conditions, but allows changes to be made to the previously established paths.

## Clos theorem

### Clos theorem:

A Clos network is **strict-sense non-blocking** if and only if the number of 2nd stage switch blocks fulfills the condition

$$r_2 \geq m_1 + n_3 - 1$$

- A symmetric Clos network with  $m_1 = n_3 = n$  is strict-sense non-blocking if

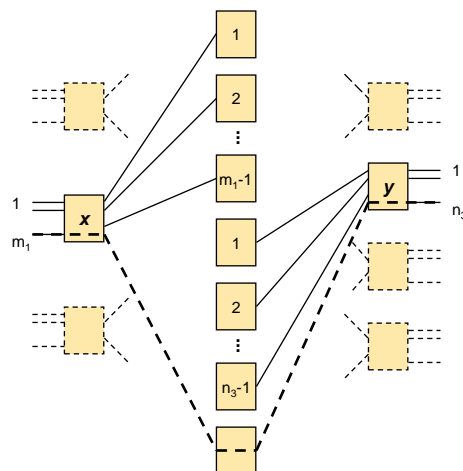
$$r_2 \geq 2n - 1$$

## Proof of Clos theorem

### Proof 1:

- Let's take some SB  $x$  in the 1st stage and some SB  $y$  in the 3rd stage, which both have maximum number of connections minus one  
 $\Rightarrow x$  has  $m_1 - 1$  and  $y$  has  $n_3 - 1$  connections
- One additional connection should be established between  $x$  and  $y$
- In the worst case, existing connections of  $x$  and  $y$  occupy distinct 2nd stage SBs  
 $\Rightarrow m_1 - 1$  SBs for paths of  $x$  has and  $n_3 - 1$  SBs for paths of  $y$
- To have a connection between  $x$  and  $y$  an additional SB is needed in the 2nd stage  
 $\Rightarrow$  required number of SBs is  $(m_1 - 1) + (n_3 - 1) + 1 = m_1 + n_3 - 1$

## Visualization of proof



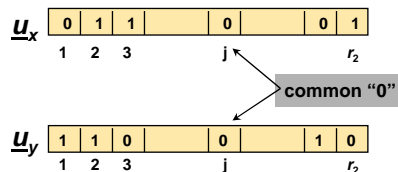
## Paull's matrix and proof of Clos theorem

### Proof 2:

- A connection from an idle input of a 1st stage SB  $x$  to an idle output of a 3rd stage SB  $y$  should be established
- $m_1-1$  symbols can exist already in row  $x$ , because there are  $m_1$  inputs to SB  $x$ .
- $n_3-1$  symbols can exist already in row  $y$ , because there are  $n_3$  outputs to SB  $y$ .
- In the worst case, all the  $(m_1-1 + n_3-1)$  symbol are distinct
- To have an additional path between  $x$  and  $y$ , one more SB is needed in the 2nd stage  
 $\Rightarrow m_1 + n_3 - 1$  SBs are needed

## Procedure for making connections

- Keep track of symbols used by row  $x$  using an occupancy vector  $\underline{u}_x$  (which has  $r_2$  entries that represent SBs of the 2nd stage)
- Enter "1" for a symbol in  $\underline{u}_x$  if it has been used in row  $x$ , otherwise enter "0"
- Likewise keep track of symbols used by column  $y$  using an occupancy vector  $\underline{u}_y$
- To set up a connection between SB  $x$  and SB  $y$  look for a position  $j$  in  $\underline{u}_x$  and  $\underline{u}_y$  which has "0" in both vectors
- Amount of required computation is proportional to  $r_2$





## Rearrangeable networks

### Slepian-Duguid theorem:

A three stage network is rearrangeable if and only if

$$r_2 \geq \max(m_1, n_3)$$

A symmetric Clos network with  $m_1 = n_3 = n$  is rearrangeably non-blocking if

$$r_2 \geq n$$

### Paul's theorem:

The number of circuits that need to be rearranged is at most

$$\min(r_1, r_3) - 1$$

## Connection rearrangement by Paul's matrix

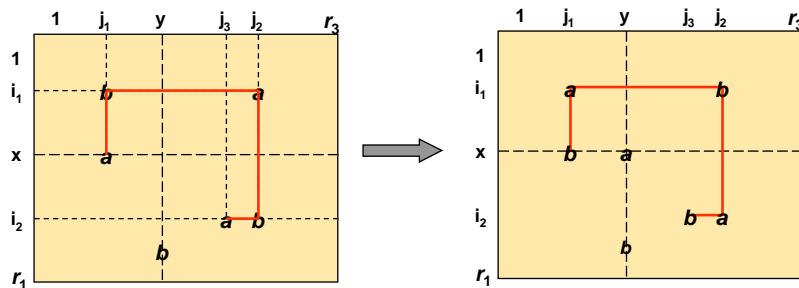
- If there is no common symbol (position  $j$ ) found in  $\underline{u}_x$  and  $\underline{u}_y$ , we look for symbols in  $\underline{u}_x$  that are not in  $\underline{u}_y$  and symbols in  $\underline{u}_y$  not found in  $\underline{u}_x$  => a new connection can be set up only by rearrangement
- Let's suppose there is symbol  $\mathbf{a}$  in  $\underline{u}_x$  (not in  $\underline{u}_y$ ) and symbol  $\mathbf{b}$  in  $\underline{u}_y$  (not in  $\underline{u}_x$ ) and let's choose either one as a starting point
- Let it be  $\mathbf{a}$  then  $\mathbf{b}$  is searched from the column in which  $\mathbf{a}$  resides (in row  $\mathbf{x}$ ) - let it be column  $\mathbf{j}_1$  in which  $\mathbf{b}$  is found in row  $\mathbf{i}_1$
- In row  $\mathbf{i}_1$  search for  $\mathbf{a}$  - let this position be column  $\mathbf{j}_2$
- This procedure continues until symbol  $\mathbf{a}$  or  $\mathbf{b}$  cannot be found in the column or row visited

|                   |   |   |              |              |   |       |
|-------------------|---|---|--------------|--------------|---|-------|
| $\underline{u}_x$ | 1 | 1 | 0            | 1            | 1 | 1     |
|                   | 1 | 2 | $\mathbf{a}$ | $\mathbf{b}$ |   | $r_2$ |

|                   |   |   |              |              |   |       |
|-------------------|---|---|--------------|--------------|---|-------|
| $\underline{u}_y$ | 1 | 1 | 1            | 0            | 1 | 1     |
|                   | 1 | 2 | $\mathbf{a}$ | $\mathbf{b}$ |   | $r_2$ |

## Connection rearrangement by Paull's matrix (cont.)

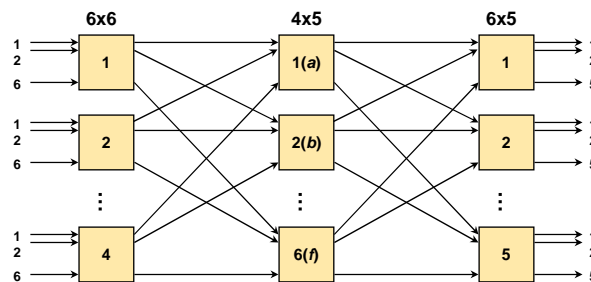
- At this point connections identified can be rearranged by replacing symbol **a** (in rows **x**,  $i_1$ ,  $i_2$ , ...) by **b** and symbol **b** (in columns **y**,  $j_1$ ,  $j_2$ , ...) by **a**
- **a** and **b** still appear at most once in any row or column
- 2nd stage SB **a** can be used to connect **x** and **y**



## Example of connection rearrangement by Paull's matrix

- Let's take a three-stage network  $24 \times 25$  with  $r_1=4$  and  $r_3=5$
- Rearrangeability condition requires that  $r_2=6$   
- let these SBs be marked by **a**, **b**, **c**, **d**, **e** and **f**

$$\Rightarrow m_1 = 6, n_1 = 6, m_2 = 4, n_2 = 5, m_3 = 6, n_3 = 5$$



## Example of connection rearrangement by Paul's matrix (cont.)

- In the network state shown below, a new connection is to be established between SB1 of stage 1 and SB1 of stage 3
- No SBs available in stage 2 to allow a new connection
- Slepian-Duguid theorem  $\Rightarrow$  a three stage network is rearrangeable if and only if  $r_2 \geq \max(m_1, n_3)$ 
  - $m_1 = 6, n_3 = 5, r_2 = 6 \Rightarrow$  condition fulfilled
- SBs **c** and **d** are selected to operate rearrangement

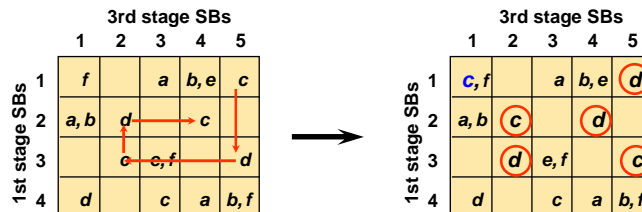
|               |   | 3rd stage SBs |   |     |     |     |
|---------------|---|---------------|---|-----|-----|-----|
|               |   | 1             | 2 | 3   | 4   | 5   |
| 1st stage SBs | 1 | f             |   | a   | b,e | c   |
|               | 2 | a,b           | d |     | c   |     |
|               | 3 |               | c | e,f |     | d   |
|               | 4 | d             |   | c   | a   | b,f |

Occupancy vectors of SB1/stage 1 and SB1/stage 3

|                       |   |   |   |   |   |   |
|-----------------------|---|---|---|---|---|---|
| $\underline{u}_{1-1}$ | 1 | 1 | 1 | 0 | 1 | 1 |
|                       | a | b | c | d | e | f |
| $\underline{u}_{3-1}$ | 1 | 1 | 0 | 1 | 0 | 1 |
|                       | a | b | c | d | e | f |

## Example of connection rearrangement by Paul's matrix (cont.)

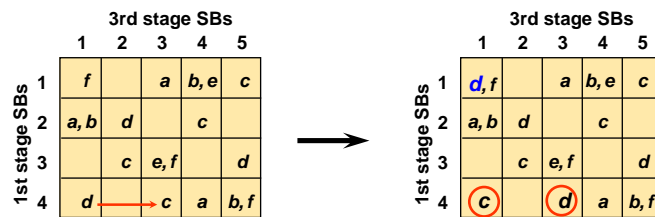
- Start rearrangement procedure from symbol **c** in row 1 and column 5



- 5 connection rearrangements are needed to set up the required connection - Paul's theorem !!!

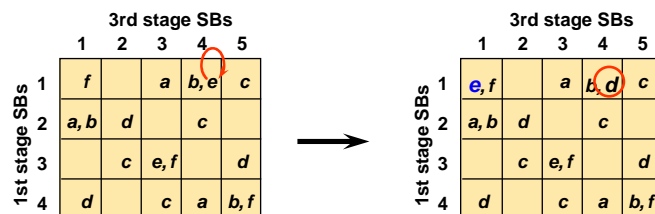
## Example of connection rearrangement by Paul's matrix (cont.)

- Paul's theorem states that the number of circuits that need to be rearranged is at most  $\min(r_1, r_3) - 1 = 3$   
=> there must be another solution
- Start rearrangement procedure from **d** in row 4 and column 1  
=> two connection rearrangements are needed



## Example of connection rearrangement by Paul's matrix (cont.)

- In this example case, it is possible to manage with only one connection rearrangement by selecting switch blocks **d** and **e** to operate the rearrangement
- Start rearrangement procedure from **e** in row 1 and column 4  
=> only one connection rearrangement is needed



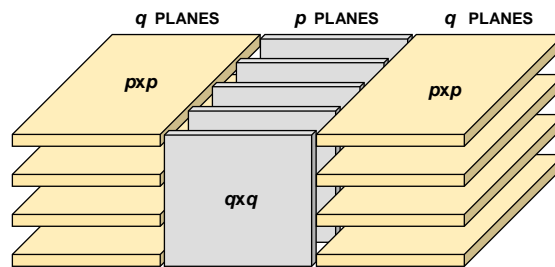
## Recursive construction of switching networks

- To reduce cross-point complexity of three stage switches individual stages can be factored further
- Suppose we want to construct an  $N \times N$  switching network and let  $N = p \times q$
- Since we have a symmetric switch then
  - $m_1 = n_3 = p$  and  $r_1 = r_3 = q$
- Considering basic relations of a Clos network
  - $r_1 = m_2, r_2 = n_1 = m_3$  and  $r_3 = n_2$we get
  - $m_2 = n_2 = q$

## Recursive construction of switching networks (cont.)

- Slepian-Duguid theorem states that a three state network is rearrangeable if  $r_2 \geq \max(m_1, n_3) \Rightarrow r_2 = p \Rightarrow n_1 = m_3 = p$
- This means that a rearrangeably non-blocking Clos network is constructed recursively by connecting a  $p \times p$ ,  $q \times q$  and  $p \times p$  rearrangeably non-blocking switches together in respective order  $\Rightarrow$  under certain conditions result may be a strict-sense non-blocking network
- Clos theorem states that a Clos network is strict-sense non-blocking if  $r_2 \geq m_1 + n_3 - 1 \Rightarrow r_2 = 2p - 1 \Rightarrow n_1 = m_3 = 2p - 1$
- This means that a strict-sense non-blocking network is constructed recursively by connecting a  $p(2p - 1)$ ,  $q \times q$  and  $p(2p - 1)$  strict-sense non-blocking switches together in respective order  $\Rightarrow$  result may be a rearrangeable non-blocking network

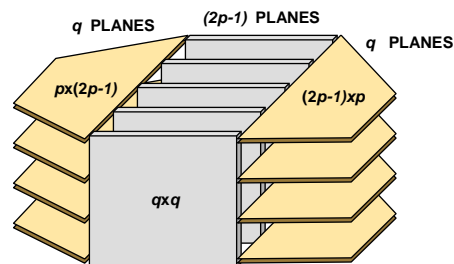
### 3-dimensional construction of a rearrangeably non-blocking network



Number of cross-points for the rearrangeable construction is

$$p^2q + q^2p + p^2q = 2p^2q + q^2p$$

### 3-dimensional construction of a strict-sense non-blocking network



Number of cross-points for the strictly non-blocking construction is

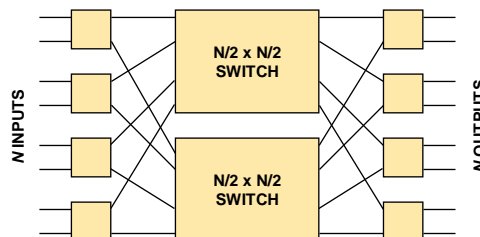
$$p(2p-1)q + q^2(2p-1) + p(2p-1)q = 2p(2p-1)q + q^2(2p-1)$$

## Recursive factoring of switching networks

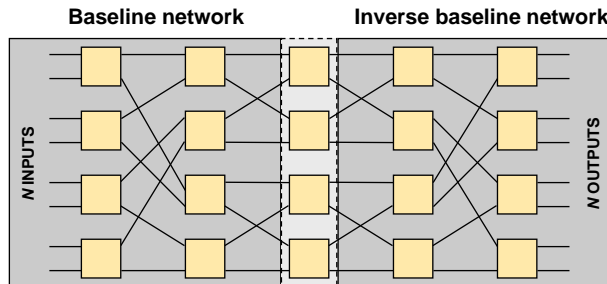
- $N$  can be factored into  $p$  and  $q$  in many ways and these can be factored further
- Which  $p$  to choose and how should the sub-networks be factored further ?
- Doubling in the 1st and 3rd stages suggests to start with the smallest factor and recursively factor  $q = N/p$  using the next smallest factor  
 $\Rightarrow$  this strategy works well for rearrangeable networks  
 $\Rightarrow$  for strict-sense non-blocking networks width of the network is doubled  
 $\Rightarrow$  not the best strategy for minimizing cross-point count
- Ideal solution: low complexity, minimum number of cross-points and easy to construct  $\Rightarrow$  quite often conflicting goals

## Recursive factoring of a rearrangeably non-blocking network

- Special case  $N = 2^n$ ,  $n$  being a positive integer  
 $\Rightarrow$  a **rearrangeable network** can be constructed by factoring  $N$  into  $p = 2$  and  $q = N/2$   
 $\Rightarrow$  resulting network is a Benes network  
 $\Rightarrow$  each stage consists of  $N/2$  switch blocks of size  $2 \times 2$
- Factor  $q$  relates to the multiplexing factor (number of time-slots on inputs)  
 $\Rightarrow$  recursion continued until speed of signals low enough for real implementations



## Benes network



Number of stages in a Benes network

$$K = 2 \log_2 N - 1$$

## Benes network (cont.)

- Benes network is recursively constructed of  $2 \times 2$  switch blocks and it is rearrangeably non-blocking (see Clos theorem)
- First half of Benes network is called baseline network
- Second half of Benes network is a mirror image (inverse) of the first half and is called inverse baseline network
- Number of switch stages is  $K = 2 \log_2 N - 1$
- Each stage includes  $N/2$   $2 \times 2$  switching blocks (SBs) and thus number of SBs of a Benes network is

$$N \log_2 N - (N/2) = N(\log_2 N - 1/2)$$

- Each  $2 \times 2$  SB has 4 cross-points and number of cross-points in a Benes network is

$$4(N/2)(2 \log_2 N - 1) = 4N \log_2 N - 2N \sim 4N \log_2 N$$



## Illustration of recursively factored Benes network

